Robust penalized inference for Gaussian Scale Mixtures
Karina Ashurbekova, Sophie Achard, Florence Forbes

To cite this version:

HAL Id: hal-02291576
https://hal.univ-grenoble-alpes.fr/hal-02291576
Submitted on 19 Sep 2019

HAL is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers.

L’archive ouverte pluridisciplinaire HAL, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d’enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.
Robust penalized inference for Gaussian Scale Mixtures

Karina Ashurbekova  
GIPSA-lab, Inria  
Univ. Grenoble Alpes  
Grenoble, France  
karina.ashurbekova@gipsa-lab.fr

Sophie Achard  
CNRS, Grenoble INP, GIPSA-lab  
Univ. Grenoble Alpes  
Grenoble, France  
sophie.achard@gipsa-lab.fr

Florence Forbes  
Inria, CNRS, Grenoble INP, LJK  
Univ. Grenoble Alpes  
Grenoble, France  
florence.forbes@inria.fr

I. Abstract

A. Brief introduction

The literature on sparse precision matrix estimation is rapidly growing and receiving significant attention from the research community [4], [3]. Many strong methods are valid only for Gaussian variables [8], [7]. One of the most commonly used approaches in this case is glasso [6] which aims to minimize the negative L1-penalized log-likelihood function:

\[ \min_{\Theta > 0} \text{tr}(\Theta S) - \log \det(\Theta) + \rho ||\Theta||_1 \]  

(1)

where \( S = \sum_{i=1}^{n} (x_i - \mu)(x_i - \mu)^T \) is the sample covariance matrix of observed independent samples \( x_1, \cdots, x_n \) from \( N(\mu, \Sigma) \), \( \Theta = \Sigma^{-1} \) is the precision matrix, \( \rho \) is a regularization parameter.

In practice, data may deviate from normality in various ways, outliers and heavy tails frequently occur that can severely degrade the Gaussian models performance. A natural solution is to turn to heavier tailed distributions that remain tractable. For this purpose, we propose a penalized version of EM-algorithm for Gaussian Scale Mixtures. The proposition we state below allows us to design the penalized EM algorithm valid for the distributions that can be seen as Gaussian Scale Mixtures.

Definition 1 (Scale mixture of multivariate Gaussian distributions).

If \( \mu \) is a \( p \)-dimensional vector, \( \Sigma \) is a \( p \times p \) positive definite symmetric matrix and \( f_W \) is a probability distribution function of a univariate positive variable \( W \in \mathbb{R}^+ \), then the \( p \)-dimensional density given by

\[ p(x; \mu, \Sigma, \theta) = \int_0^\infty N_p\left( x; \mu, \Sigma \right) f_W(w; \theta) \, dw \]  

(2)

is said to be a scale mixture of Gaussian densities with mixing distribution function \( f_W \). If vector \( X \) has density (2), we write \( X \sim \text{GSM}_p(\mu, \Sigma, \theta) \) and we refer to \( W \) as the mixing variable.

Proposition 1. Let \( X \sim \text{GSM}_p(\mu, \Sigma, f_W) \) and \( W \) denote the mixing variable. Then \( X \) has an elliptical distribution

\[ p(x; \mu, \Sigma, f_W) = \frac{2}{\pi} \frac{1}{|\Sigma|} \frac{1}{g(t)} \exp\left(-\frac{1}{2}t^T\Sigma^{-1}t\right) \]  

with generator \( g(t) = g(t) = \int_{0}^{\infty} w^2 \exp\left(-\frac{1}{2}tw\right)f_W(w) \, dw \). It follows that

\[ E[W|x, \Psi] = -\frac{\partial g'(t(x - \mu)T\Sigma^{-1}(x - \mu))}{g(t(x - \mu)T\Sigma^{-1}(x - \mu))} \]  

where \( g' \) is the derivative of \( g \).

B. Penalized EM algorithm for Gaussian Scale Mixtures

Like in the Gaussian case, we put a L1-norm penalty on the elements of the matrix \( \Theta \) and wish to maximize the penalized log-likelihood function. Let us consider \( n \) i.i.d. variables \( x_i \), following a \( \text{GSM}_p(\mu, \Sigma, f_W) \) distribution for \( i = 1 : n \), the model parameters to estimate are \( \Psi = \{ \mu, \Sigma, \theta \} \). Introducing the corresponding latent variables \( \{ W_i, i = 1 : n \} \), we can consider an EM algorithm. The expected complete likelihood \( Q(\Psi, \Psi^{(r-1)}) \) at iteration \( r \) of the algorithm takes the form:

\[ Q(\Psi, \Psi^{(r-1)}) = \sum_{i=1}^{n} E \left[ \log p(x_i|W_i; \mu, \Sigma)|x_i, \Psi^{(r-1)} \right] + \]  

\[ + E \left[ \log f_W(W_i)|x_i, \Psi^{(r-1)} \right] - \rho ||\Sigma^{-1}||_1 \]  

(3)

By definition the distribution of \( (x_i|x_i = W_i = w_i) \) is \( N(\cdot; \mu, \Sigma(w)) \) and does not depend on \( \theta \).

The E-step is the same as for non-penalized version. For \( i = 1 : n \), compute \( E[W_i|x_i, \Psi^{(r-1)}] \) according to Proposition 1 we get:

\[ E[W_i|x_i, \Psi^{(r-1)}] = \frac{-2g'(\delta(x_i, \mu^{(r-1)})\Sigma^{(r-1)})}{g(\delta(x_i, \mu^{(r-1)})\Sigma^{(r-1)})} \]  

where \( \delta(x, \mu, \Sigma) = (x - \mu)^T\Sigma^{-1}(x - \mu) \) is the Mahalanobis distance between \( x \) and \( \mu \).

For the updating of \( \Psi \), the M-step consists of two independent steps for \( \{ \mu, \Sigma \} \) and \( \theta \) respectively. The update for the vector \( \mu \) as well as for parameter \( \theta \) has the same form as for non-penalized version of EM. In contrast with the non-penalized version, the update value \( \Psi^{(r)} \) is found by solving the following optimization problem:

\[ \min_{\Theta > 0} \text{tr}(\Theta S^{(r)}) - \log \det(\Theta) + \rho ||\Theta||_1 \]  

(4)

where a “weighted sample covariance matrix” \( S^{(r)} \) and vector \( \mu \) are computed as \( S^{(r)} = \frac{1}{n} \sum_{i=1}^{n} \bar{w}_i(x_i - \mu^{(r)})(x_i - \mu^{(r)})^T \) and \( \mu^{(r)} = \frac{1}{n} \sum_{i=1}^{n} \bar{w}_i x_i \). Note that (4) is a similar objective function minimized by glasso, so that the proposed penalized algorithm reduces to solving at each iteration a glasso optimization problem. There is no need to inverse the matrix \( \Sigma \) on each step since for all \( i = 1 : n \) the variables \( \bar{w}_i \) depend on \( \Theta^{(r-1)} \) and not on \( \Sigma^{(r-1)} \). Moreover, it is shown in [1] that the optimization problem 4 can be replaced by more efficient CLIME algorithm [2].

C. Results

As a particular example of the described approach, Finegold and Drton [5] proposed a tlasso procedure for multivariate t-distribution. We compare the results of tlasso, CLIME [1] which a modified version of tlasso, CLIME [3] and EPIC method [9] designed for elliptical distributions. To measure how well the sparsity of the true precision matrix is recovered, we plot ROC curves presented in Figure 1. For Gaussian data, the tCLIME and EPIC performance is similar and better than that of tlasso and CLIME. When data is generated from a t-distribution, CLIME significantly outperforms tCLIME and also shows better results than EPIC and tlasso.

Index Terms—Structure learning, Gaussian Scale Mixtures, Gaussian graphical model, t-distribution, sparse precision matrix estimation, robust estimation
Fig. 1: ROC curves illustrating the performance of tlasso, CLIME, tCLIME and EPIC methods on 2 different data sets. A random $100 \times 100$ sparse precision matrix $\Theta$ is generated according to the procedure described in [5]; $n=150$ observations are simulated from $t_{100}(0, \Theta^{-1}, 3)$ and $N_{100}(0, \Theta^{-1})$. The four algorithms are then run with different values of $\rho$ and the whole process is repeated 50 times. The tuning parameter $\rho$ is chosen in the range $[0.1, 2.5]$ with stepsize 0.05 for tlasso and $[0.01, 0.4]$ with stepsize 0.01 for CLIME, tCLIME and EPIC.

REFERENCES